

# What to do next?

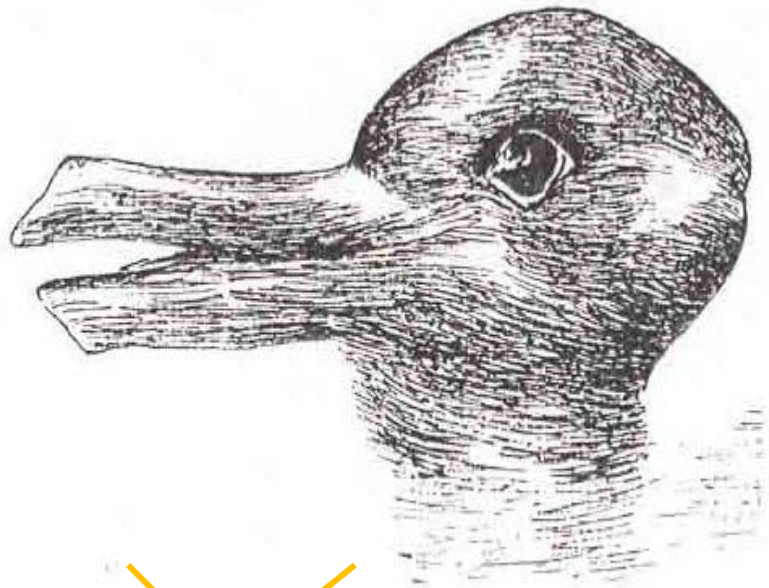
- *on top down task driven feature saliency*

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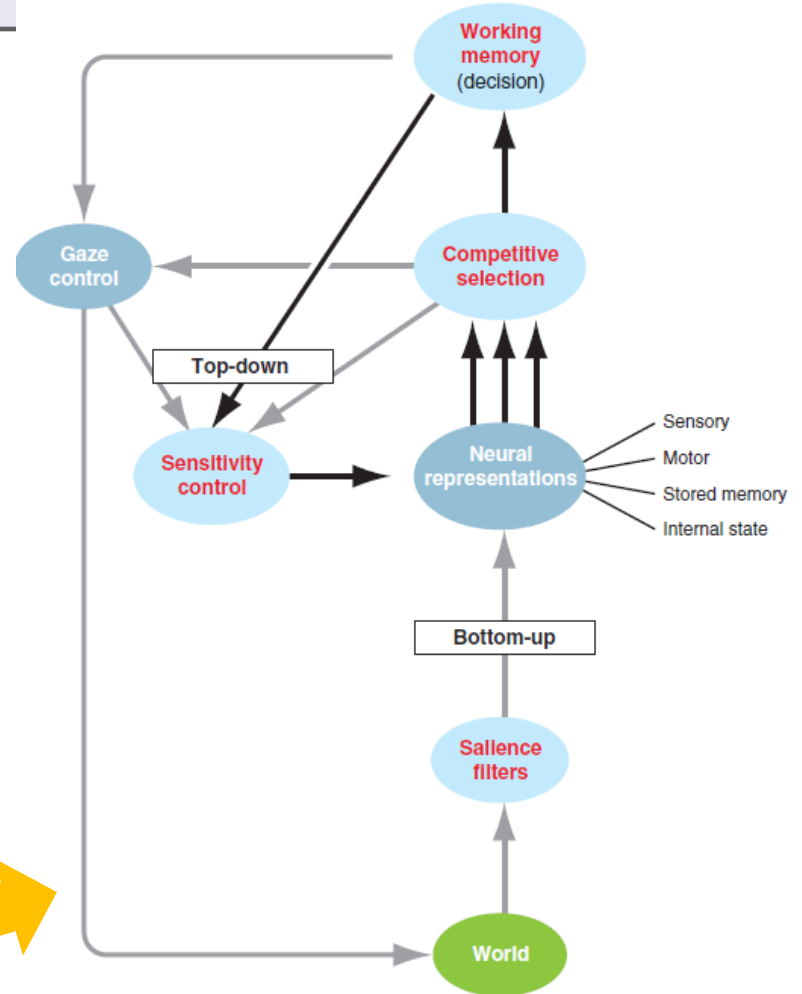


# Motivating example



~~BIRD~~

RABBIT



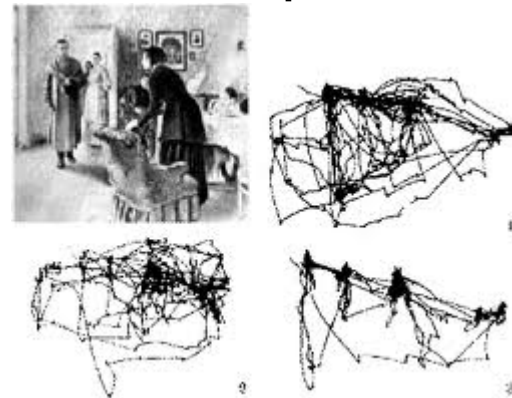
E.I. Knudsen: Fundamental Components of Attention, Annu. Rev. Neurosci. 2007. 30:57–78.

# Why pursue top down attention mechanisms?

- Predictive modeling of human behavior



- Inverse reconstruct human intention /sphere of interest from actions



V. Navalpakkam, L. Itti, Modeling the influence of task on attention, *Vision Research*, Vol. **45**, No. 2, pp. 205-231, Jan 2005.

# Top down vs bottom up attention

## Bottom up

Attention determined by  
feature of the input

### Audio

Cocktail party effect  
(Cherry, 64)

### Visual

Classical spatial  
novelty saliency  
(Itti+Koch, 04)

## Top down

Attention determined by  
state of the observer

### Audio

Cocktail party  
problem (Cherry, 64)

### Visual

ambiguous pictures  
eye tracking

See e.g. J.M. Wolfe et al. "How fast can you change your mind? The speed of top-down guidance in visual search" *Vision Research* 44 (2004) 1411–1426

# A model of top down attention

**1.** Task is implemented as decision problem

Standard probabilistic classifier

Model of posterior probability

$$p(c|x,z)$$

**2.** Attention is represented as choice of feature

Two sets of features

- i) Features setting the context **'the gist (x)**  
(Friedman, 79; Torralba et al., 04)
- ii) **Potential features (z)** considered by the attention mechanism

Friedman A. Framing pictures: the role of knowledge in automatized encoding and memory of gist. Journal of Experimental Psychology: General 1979; 108: 316–355.

# Mathematical model

The **GIST**

We are interested in a partial observation  $\mathbf{x}$  under a decision task: Choose among "C" actions

$$\begin{aligned} p(c|\mathbf{x}) &= \int p(c, \mathbf{z}|\mathbf{x}) d\mathbf{z} \\ &= \frac{\int p(c, \mathbf{x}, \mathbf{z}) d\mathbf{z}}{\sum_{c=1}^C \int p(c, \mathbf{x}, \mathbf{z}) d\mathbf{z}} \end{aligned}$$

versus getting additional information through  $z_j$

$$\begin{aligned} p(c|\mathbf{x}, z_j) &= \sum_{c=1}^C \int p(c, \mathbf{z}|\mathbf{x}) \prod_{i \neq j} dz_i \\ &= \frac{\int p(c, \mathbf{x}, \mathbf{z}) \prod_{i \neq j} dz_i}{\sum_{c=1}^C \int p(c, \mathbf{x}, \mathbf{z}) \prod_{i \neq j} dz_i} \end{aligned}$$

# Measure the information gain

First used by Lindley (1956) for experimental design..

## ON A MEASURE OF THE INFORMATION PROVIDED BY AN EXPERIMENT<sup>1, 2</sup>

BY D. V. LINDLEY

*University of Cambridge and University of Chicago*

**1. Summary.** A measure is introduced of the information provided by an experiment. The measure is derived from the work of Shannon [10] and involves the knowledge prior to performing the experiment, expressed through a prior probability distribution over the parameter space. The measure is used to compare some pairs of experiments without reference to prior distributions; this method of comparison is contrasted with the methods discussed by Black-  
1. Finally, the measure is applied to provide a solution to some problems of experimental design, where the object of experimentation is not to reach decisions but rather to gain knowledge about the world.

D. V. Lindley, "On a measure of the information provided by an experiment," *Annals Mathematical Statistics*, vol. 4, pp. 986–1005, 1956.

# Information theoretical model

$$\Delta S_j(\mathbf{x}, z_j) = - \sum_{c=1}^C \int \log p(c, \mathbf{z} | \mathbf{x}) p(c, \mathbf{z} | \mathbf{x}) dz$$
$$+ \sum_{c=1}^C \log p(c | \mathbf{x}, z_j) p(c | \mathbf{x}, z_j)$$

$$G_j(\mathbf{x}) \equiv \int \Delta S_j(\mathbf{x}, z_j) p(z_j | \mathbf{x}) dz_j$$
$$= \sum_{c=1}^C \int \log p(c | \mathbf{x}, z_j) p(c, z_j | \mathbf{x}) dz_j$$
$$- \sum_{c=1}^C \int \log p(c, \mathbf{z} | \mathbf{x}) p(c, \mathbf{z} | \mathbf{x}) dz.$$



# Gaussian-Discrete distribution

... allows closed form marginalization and conditionals

$$p(c, \mathbf{x}, \mathbf{z}) = \sum_{k=1}^K p(k)p(c|k)p(\mathbf{x}, \mathbf{z}|k)$$


Component probabilities

Class emission probabilities

Joints Gaussian component density of "gist" and features

# Information gain by requesting of j'th feature

1D integrals over normal distribution pdf

$$G_j(\mathbf{x}) = \sum_{c=1}^C \sum_{k=1}^K p(c|k)p(k|\mathbf{x}) \times \int \log [p(c, \mathbf{x}, z_j)] p(z_j|\mathbf{x}, k) dz_j - \sum_{k=1}^K p(k|\mathbf{x}) \int \log [p(\mathbf{x}, z_j)] p(z_j|\mathbf{x}, k) dz_j + \text{const.}$$


# Experimental design

Consider a conventional classification problem

Train the Gaussian-discrete joint input (gist/feature) distribution on training data

Test with split gist+feature input: Give the gist ( $\mathbf{x}$ ) and determine by the information gain which feature "j" is **best**

Compare: **train**, **features**, **only gist**, **gist + best**, gist + random

# Results:

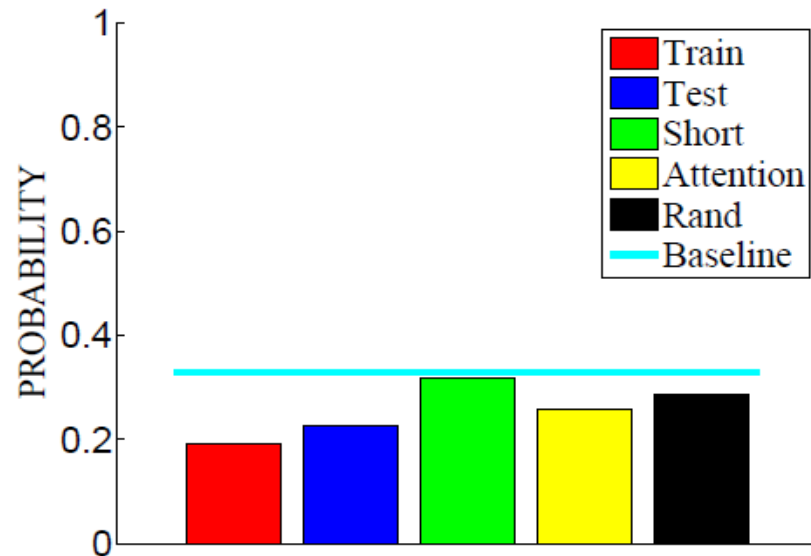
## Pima diabetes problem (UCI)

### Features

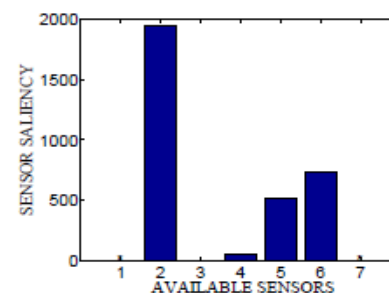
- 1\*) number of times pregnant
- 2) plasma glucose concentration a 2 hours in an oral glucose tolerance test
- 3) diastolic blood pressure
- 4) triceps skin fold thickness
- 5) body mass index
- 6) diabetes pedigree function
- 7\*) age (years).

$N_{\text{train}} = 200$

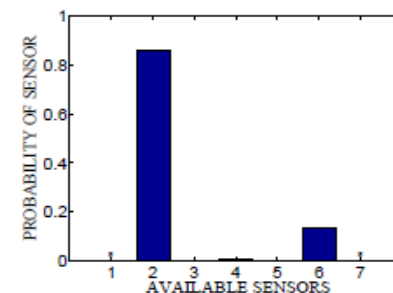
$N_{\text{test}} = 332$



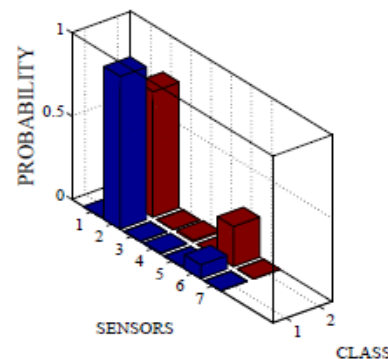
(a)



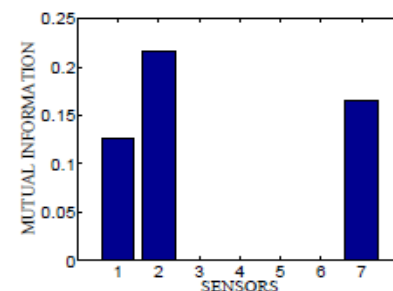
(b)



(c)



(d)



(e)

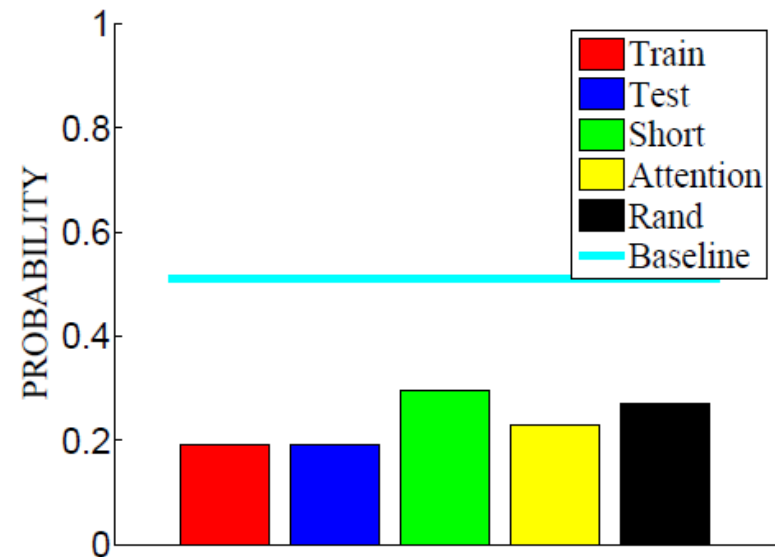
# Results:

## Abalone age classification problem

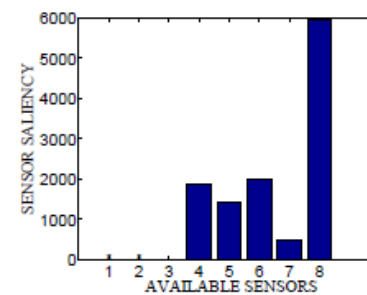
### Features:

- 1\*) gender (M, F),
- 2\*) length, longest shell measurement,
- 3) diameter, perpendicular to length,
- 4) height, with meat in shell,
- 5) whole weight, whole abalone,
- 6) shucked weight, weight of meat,
- 7) viscera weight, gut weight (after bleeding),
- 8) shell weight, after being dried.

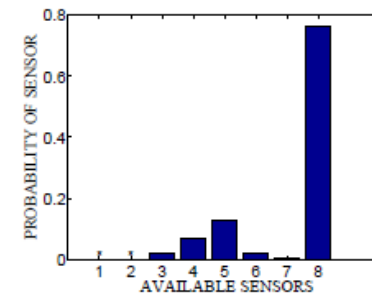
$N_{\text{train}} = 3500$     $N_{\text{test}} = 677$



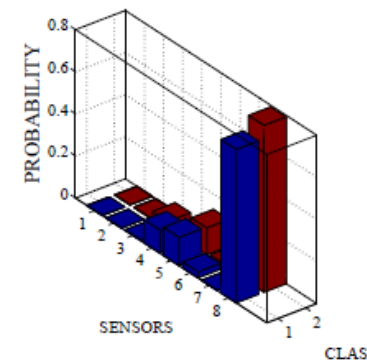
(a)



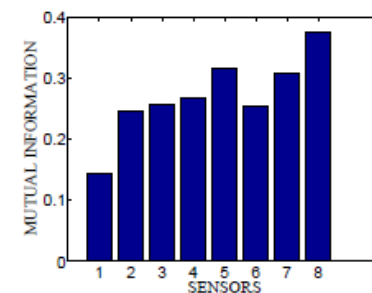
(b)



(c)



(d)



(e)

# Conclusion

- Attention mechanisms combine properties of the input field and the state/goal/task of the beholder
- A simple information optimizing mechanism can **use task information to determine what to do next and improves decision making**
- Perspectives
  - Engineering Q: Fast evaluation of a proxy for the entropy
  - Scientific Q: Are human observers optimal?
  - Cognitive Systems Q: Top-down attention can be used to infer the state of the beholder

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